Computational Geometry TU Braunschweig, Algorithms Division

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Question Sheet 1

Submit in your solutions, in a properly formatted, single, PDF file, to https://nextcloud. ibr.cs.tu-bs.de/s/p5pNRkgYMJE9F5Z. The deadline is December 21, 2023. Please additionally note the following data: Full name, field of study, and matriculation number. Please name the file as follows: [your_full_name]_[your_matriculation_number].pdf

We consider these problems in the two-dimensional variant. Please explain your answers.

Question 1 (Convex hull):

- a) Provide a definition of the convex hull of a set of points in the plane.
- b) What is the fastest feasible runtime guarantee of an algorithm which computes it?
- c) What is your favorite algorithm that computes the convex hull? Explain why!

Question 2 (Closest pair):

- a) Explain the basic idea of the divide-and-conquer algorithm for computing the closest pair of a set of points.
- b) What is the key observation in the merging step of Bentley's and Shamos' algorithm?
- c) Is it possible for the closest pair to lie on the convex hull of the point set? Why?

Question 3 (Voronoi diagram):

- a) In your own words, what is the intuitive idea of a Voronoi diagram?
- b) Explain the relationship between Voronoi cells, Voronoi vertices, and Voronoi edges.
- c) Is there a relationship between the convex hull of a point set and its Voronoi diagram?
- d) What is your favorite property of a Voronoi diagram? Why?

Question 4 (Miscellaneous):

- a) What does it mean for an algorithm to be output-sensitive? Describe a scenario in which such an algorithm may be preferable over another with better runtime bounds.
- b) What is a randomized algorithm? Do you know any? Explain its idea.
- c) How and how fast can we compute the median of a set of n integers? And of a set of n points in the plane?

(3 Points points)

(3 Points points)

(3 Points points)

(4 Points points)

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