

Computational Geometry - Exercise Meeting \#4
December $15^{\text {th }}, 2022$

## Refresh - Higher order Voronoi diagrams



## Refresh - Higher order Voronoi diagrams



## Refresh - Higher order Voronoi diagrams



## Refresh - Higher order Voronoi diagrams



## Refresh - Farthest Point Voronoi diagrams

$$
(n-1) \text { th order }
$$



Can be computed incrementally, or directly

$$
\text { in } O(n \log n)
$$

## Farthest point Voronoi diagrams - Properties

$$
(n-1) \text { th order }
$$

The ( $n-1$ )th order Voronoi region of a point is non-empty exactly if the point is part of the set's convex hull.

All cells are unbounded, the planar graph is a tree.

## Farthest point Voronoi diagrams - Properties

$$
(n-1) t h \text { order }
$$



## Farthest point Voronoi diagrams - Properties



Edges are equidistant to two sites, closer to all others.


Vertices are equidistant to at least three sites, closer to all others.

## Smallest enclosing disk (1-center problem)

Provided a set of points $P$ in the plane, find a disk $\boldsymbol{m d}(\boldsymbol{D})$ with minimal radius $\boldsymbol{r}$ that contains all members of $P$. Assume that no three points in $P$ are collinear.


What can we say about an optimal disk $D$ ?

## Smallest enclosing disk - Uniqueness

For any point set $P$, the smallest enclosing disk $m d(P)$ is unique.


## Smallest enclosing disk - Relation to diameter



## Smallest enclosing disk - Relation to diameter



## Finding the smallest enclosing disk

Provided a set of points $\boldsymbol{P}$ in the plane, find a disk $\boldsymbol{m d}(\boldsymbol{D})$ with minimal radius $\boldsymbol{r}$ that contains all members of $P$. Assume that no three points in $P$ are collinear.


How long would a naive approach take, at most?

Any ideas how we can find an approximate min disk?

## Smallest enclosing disk - 2-Approximation



1. Pick any point $p \in P$
2. Find the farthest point $p^{\prime}$
3. Draw a circle.

## Smallest enclosing disk $-\sqrt{2}$-Approximation by bounding box

1. Compute an axisaligned bounding box


## Smallest enclosing disk $-\sqrt{2}$-Approximation by bounding box

1. Compute an axisaligned bounding box
2. Place a circle on the corners.


## Smallest enclosing disk - Optimal solution in $O(n \log n)$

CLOSEST-POINT PROBLEMS<br>Michael Ian Shamos ${ }^{\dagger}$ and Dan Hoey<br>Department of Computer Science, Yale University<br>New Haven, Connecticut 06520

## Abstract

A number of seemingly unrelated problems involving the proximity of $N$ points in the plane are studied, s
as finding a Euclidean minimum spanning tree, the smallest circle enclosing the set, $k$ nearest and farthest neighbors, the two closest points, and a proper straight-line triangulation. For most of the problems consi a lower bound of $O(N \log N)$ is shown. For all of them the best currently-known upper bound is $O\left(N^{2}\right)$ or wors The purpose of this paper is to introduce a single geometric structure, called the Voronoi diagram, which ca constructed rapidly and contains all of the relevant proximity information in only linear space. The Vorono diagram is used to obtain $O(N \log N)$ algorithms for all of the problems.

Farthest Point Voronoi Diagrams - Properties
 sites, closer to all others.

## Farthest point Voronoi diagrams - Properties

Farthest Point Voronoi Diagrams - Properties


$m d(P)$ is defined by the farthest pair or by three sites, so:

1. Check if the smallest disk on the farthest pair fits.
2. Otherwise, check all circles
 induced by highest-order Voronoi vertices.

## $\boldsymbol{k}$-center problem (NP-hard)

Provided a set of points $\boldsymbol{P}$ in the plane, find $\boldsymbol{k}$ disks $\boldsymbol{D}_{\boldsymbol{i}}$ with minimal radii $\boldsymbol{r}_{\boldsymbol{i}}$ that, when combined, contain all members of $\boldsymbol{P}$.


## Roundness



## Roundness - Metric: Smallest annulus



## Roundness - Three kinds of annuli



## Roundness - Three kinds of annuli



Outer circle via three points:

- Center lies on a vertex of the farthest point Voronoi diagram
- Inner circle is defined by closest point to this vertex


## Roundness - Three kinds of annuli



Inner circle via three points:

- Center lies on a vertex of the first-order Voronoi diagram
- Outer circle is defined by farthest point from this vertex


## Roundness - Three kinds of annuli



Each circle via two points:

- Center lies on the intersection of an edge of the first-order Voronoi diagram and the farthest point diagram


## What about outliers?



## What about outliers?


"[...] $n$ points in the plane and an integer $k$ with $1 \leq k \leq n$, the problem asks to find a minimum-width annulus that contains at least $n-k$ input points."

