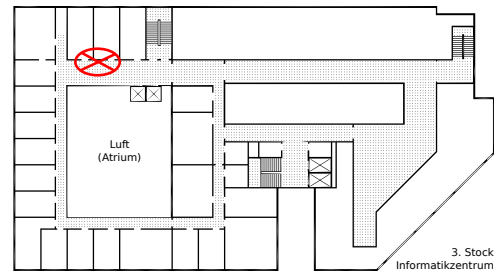


Michael Hemmer

## Geometric Algorithms Exercise 1 April 29, 2014

This sheet is comprised of several exercise. Most of them are theoretical but some are also applied, i.e., coding tasks. The solutions should be handed in by **May 6.** This can be done either at the beginning of the lecture or by placing them in the appropriate box of the exercise locker, see floor plan on the right. Applied exercises should be handed in via email to [hemmer@ibr.cs.tu-bs.de](mailto:hemmer@ibr.cs.tu-bs.de). Please mark those exercises that you would like to present during the tutorial.



In order to achieve the “*Studienleistung*”, you must have presented at least three exercises until the end of the term. Moreover, you must pass the midterm exam at the beginning of June.

### Exercise T1 (Smallest Enclosing Disk):

The expected run time of the randomized incremental algorithm presented in the lecture is  $O(n)$ .

- a) What is the worst case complexity of this algorithm ?
- b) Design a set of points and insertion order that realizes this worst case complexity.

### Exercise T2 (Expected Value):

Let  $X$  and  $Y$  be two independent random variables. Show that

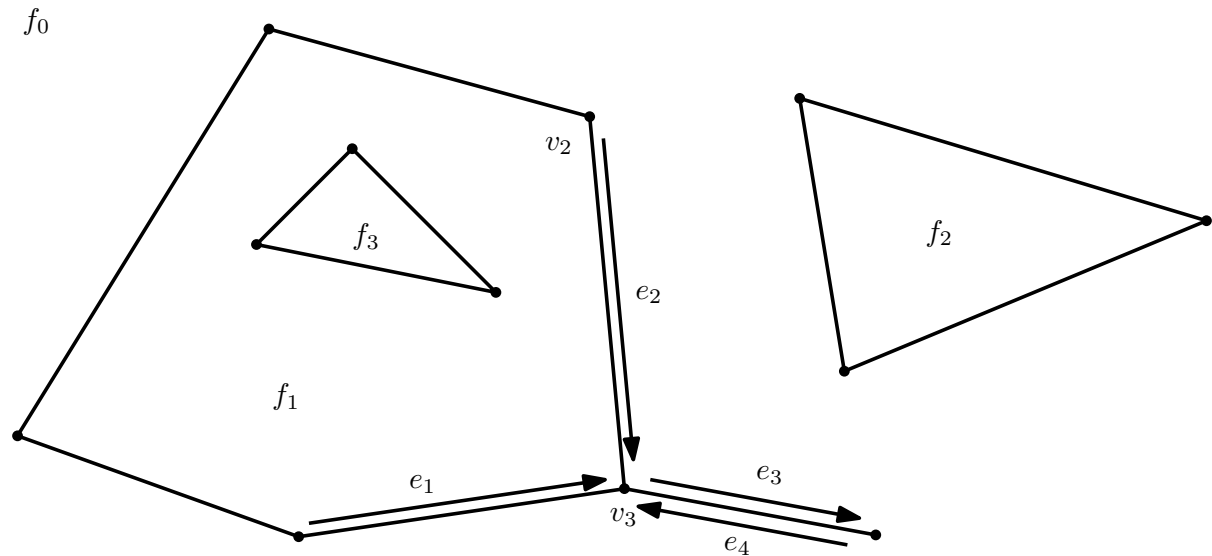
$$E[X \cdot Y] = E[X] \cdot E[Y].$$

### Exercise T3 (Randomized Incremental Construction - Backward Analysis):

Consider an algorithm that constructs a binary search tree  $T$  via randomized incremental construction. That is, the algorithm selects a random insertion order in the beginning and then constructs the tree by inserting the elements without any balancing operations. Given a set of elements  $S$  of cardinality  $n$  and another query point  $p$ . Show that the expected query time to located  $p$  in  $T$  is  $O(\log n)$ .

Hint: Consider the path in  $T$  to  $p$  already during construction. What is the probability that the length of the path increases due to an insertion of an element ?

### Exercise T4 (Doubly Connected Edge List):



a) Consider the picture above, given a call sequence to reach:

- $v_3$  from  $e_1$
- $e_4$  from  $e_1$
- $f_1$  from  $e_4$
- $f_1$  from  $f_3$
- $f_0$  from  $e_1$

For instance, we can reach  $v_3$  from  $e_2$  by:

$$v_3 = e_2.next().source()$$

- b) Given the set of all edges. How could one easily identify  $e_3$  and  $e_4$ ?
- c) Give a general function to iterated over all faces starting from the infinite face  $f_0$ .

For an advanced implementation of the interface you may want to have a look at:

[http://doc.cgal.org/latest/Arrangement\\_on\\_surface\\_2/classCGAL\\_1.1Arrangement\\_\\_2.html](http://doc.cgal.org/latest/Arrangement_on_surface_2/classCGAL_1.1Arrangement__2.html)

### Exercise P1 (Intersection Points):

Implement the algorithm *NaiveIntersect* and *SimpleIntersect* from the lecture to compute the set of all intersection points for a given set of segments.