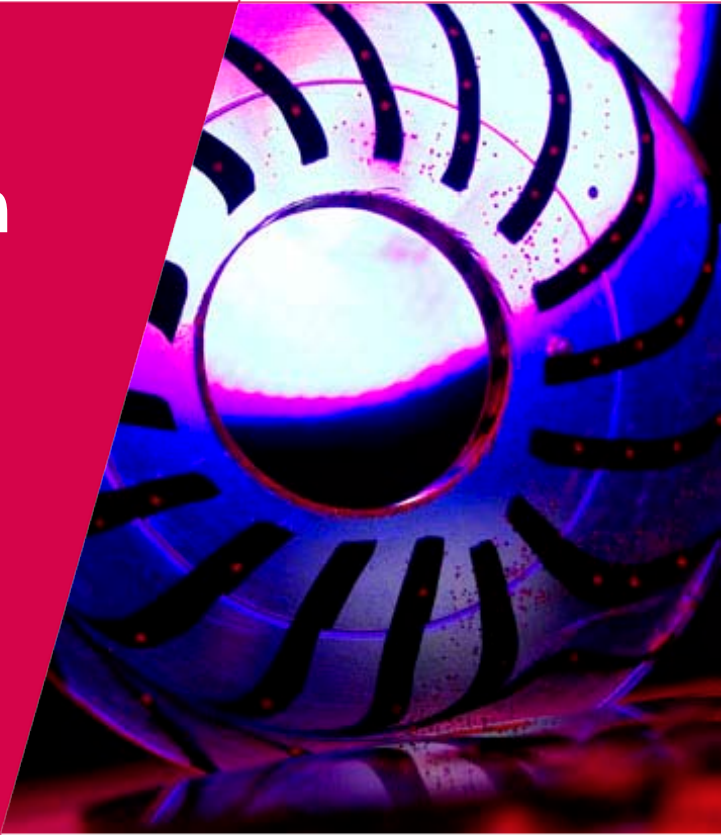


Translating synchronous to asynchronous communication and vice versa.

Jan Friso Groote



TU / **e**

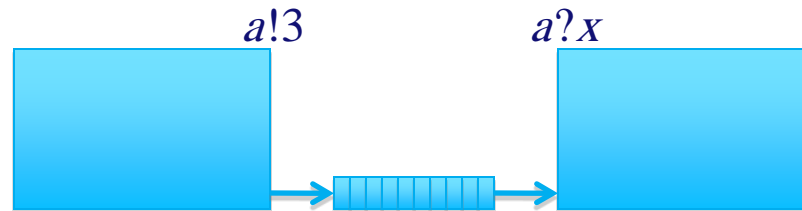
Technische Universiteit
Eindhoven
University of Technology

Where innovation starts

About which notion of (a)synchrony are we talking?

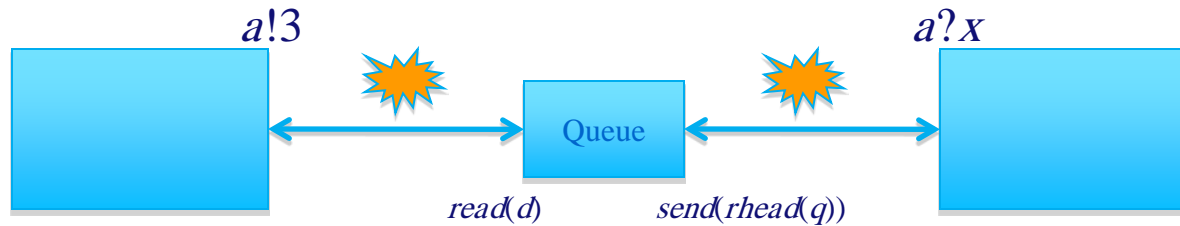
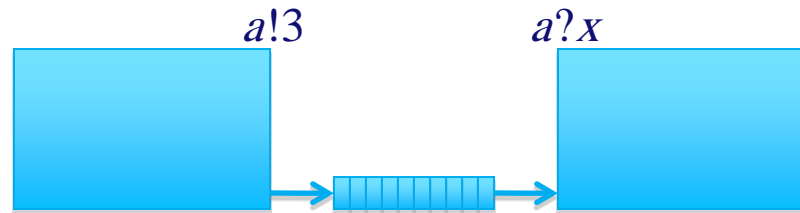


Synchronous communication: common in modelling



Asynchronous communication: common in implementation

Asynchronous \rightarrow synchronous

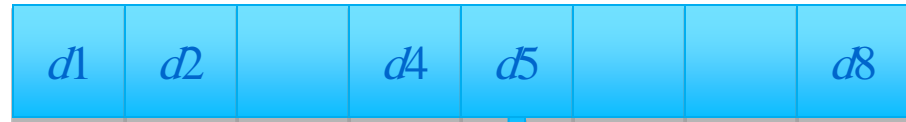


$$\begin{aligned} Queue(q.List(D)) = & \sum_{d:D} read(d).Queue(d \triangleright q) \\ & + (\neg empty(q)) \rightarrow send(rhead(q)).Queue(rtail(q)); \end{aligned}$$

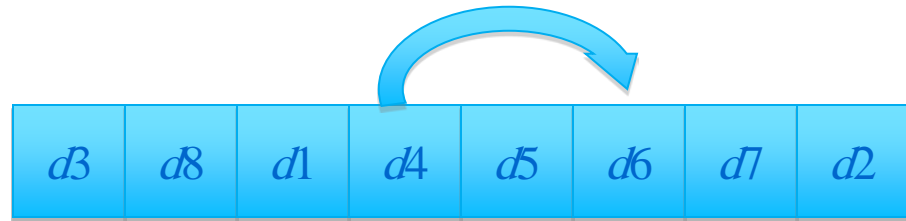
www.mcrl2.org

Asynchrony ≠ asynchrony

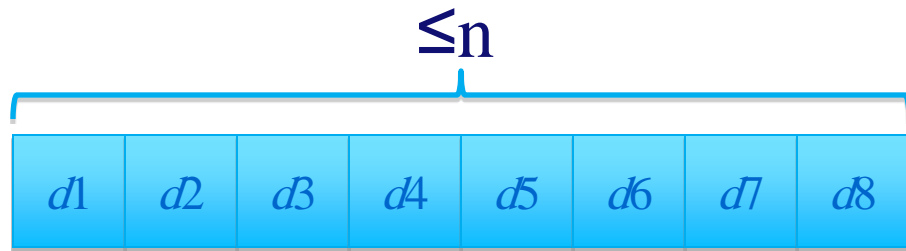
Lossy queue



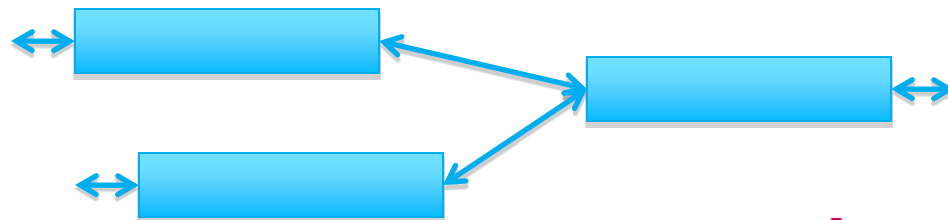
Priority queue



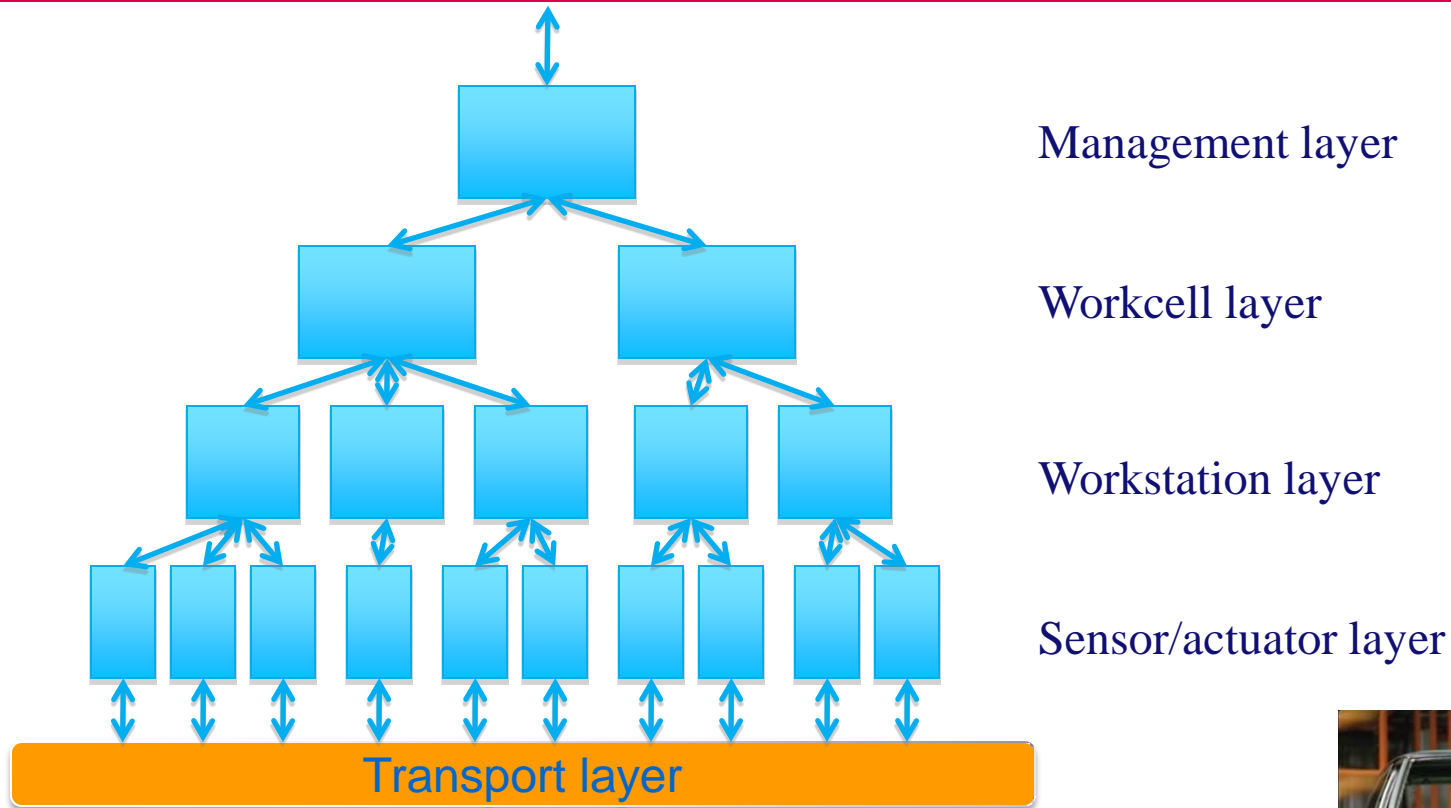
Bounded queue



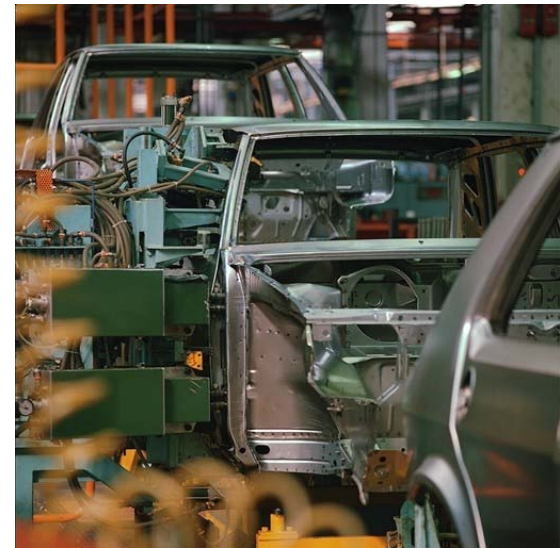
Complex queue topologies



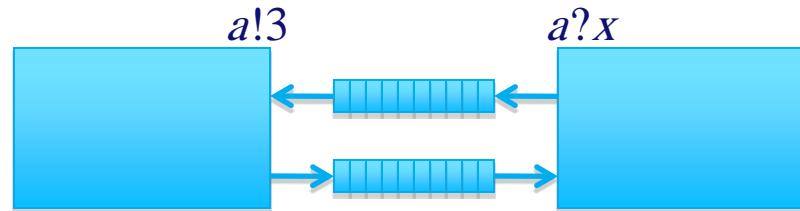
1986: Philips Computer Integrated Manufacturing architecture (Biemans, Sjoerdsma)



CIM architecture fully described in LOTOS
How to implement this synchronous language?

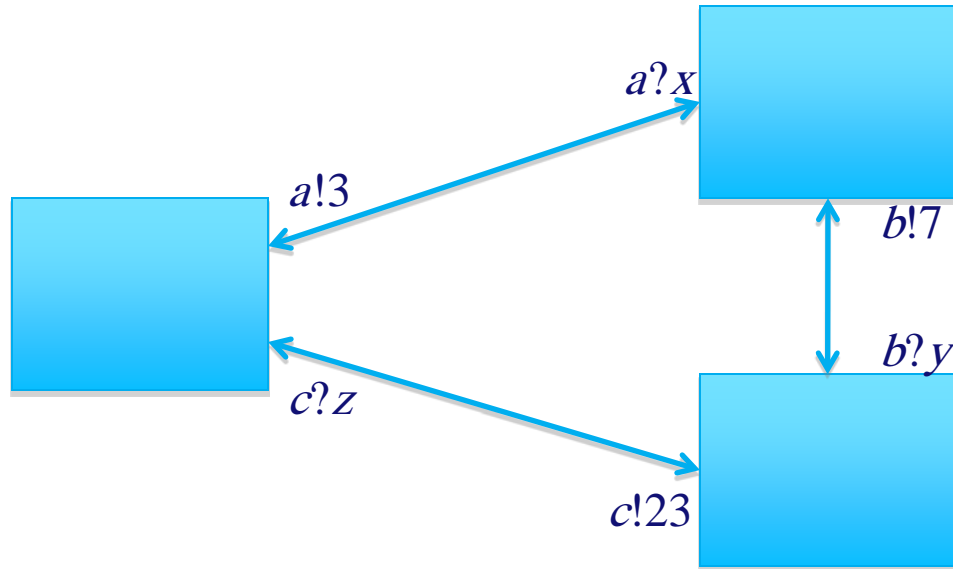


Synchronous → asynchronous



Buckley & Silberschatz 1983
Ramesh 1987
Occam & transputer

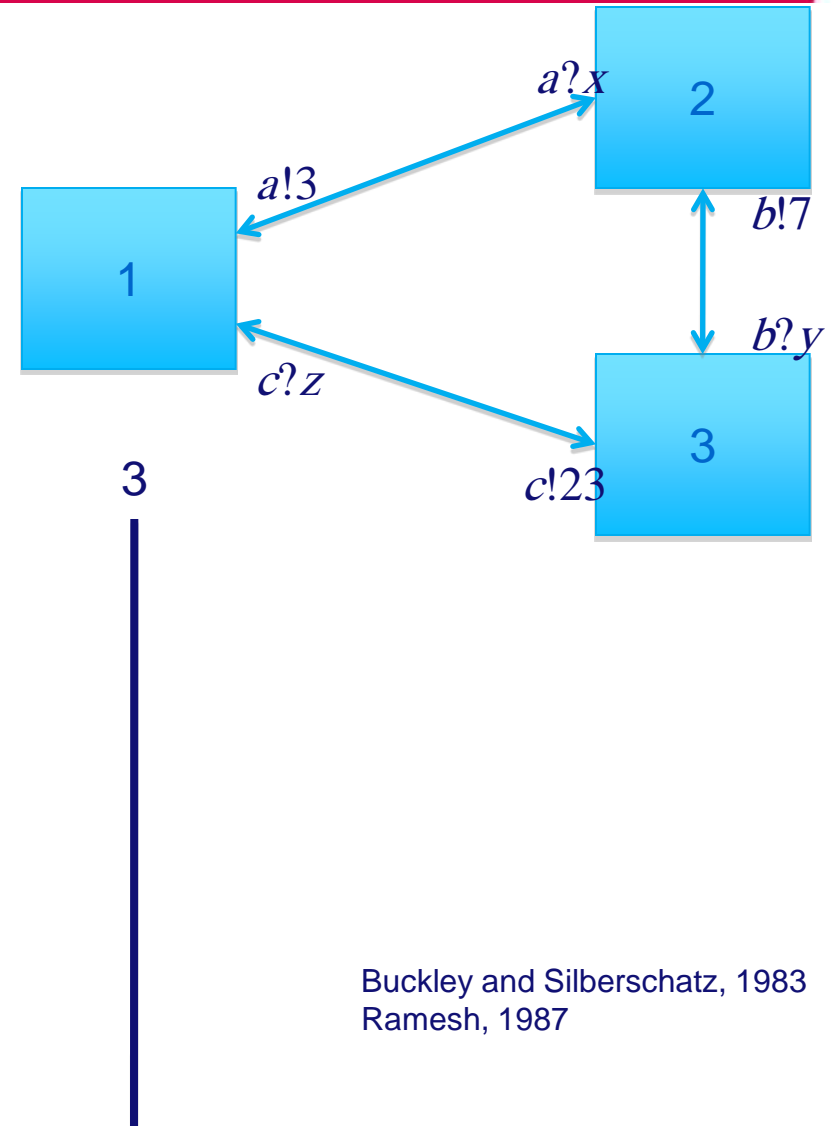
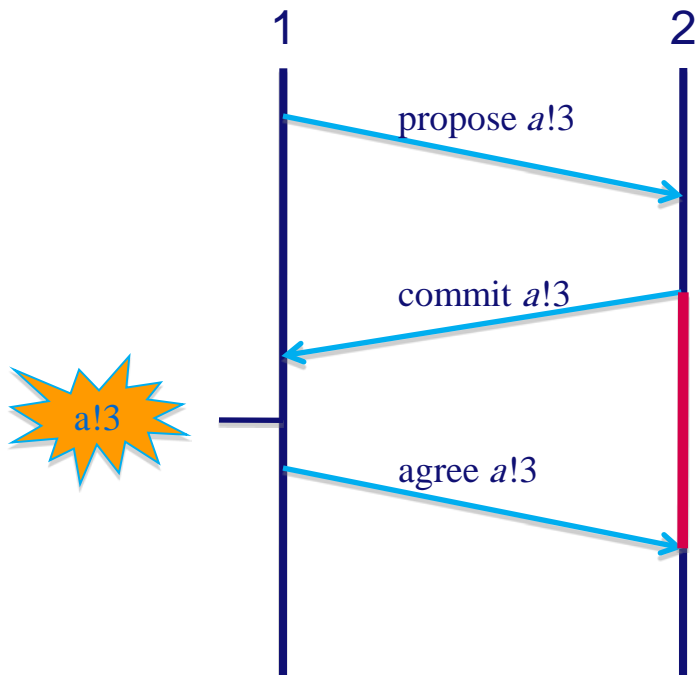
What is the problem? Conflicting interactions.



Which action will occur? $a!3$, $b!7$ or $c!23$

Solution.

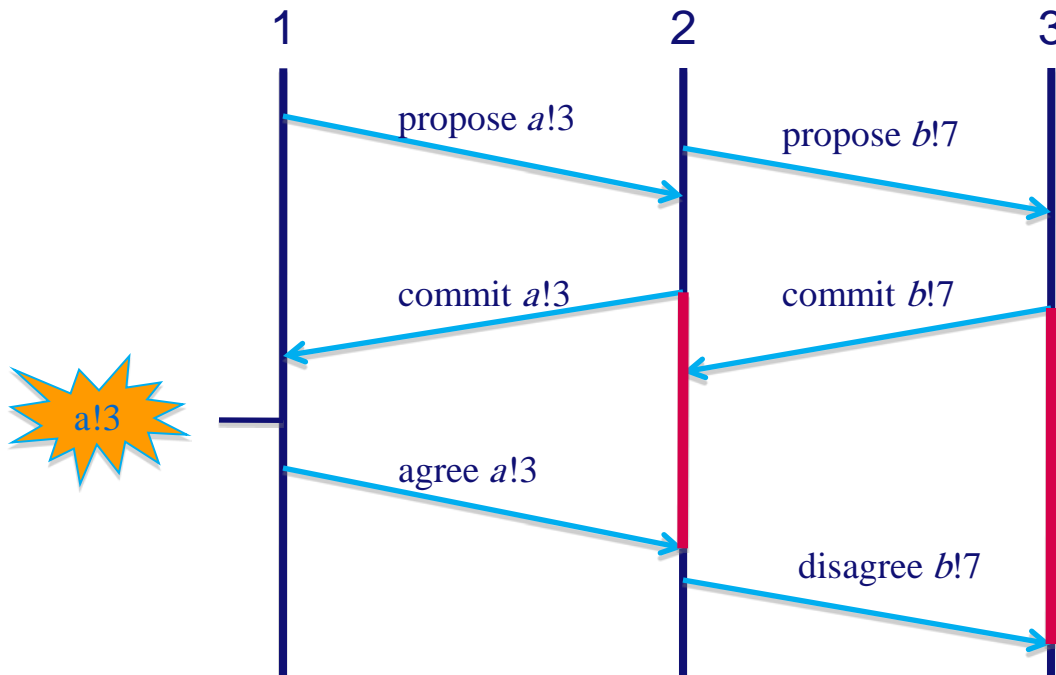
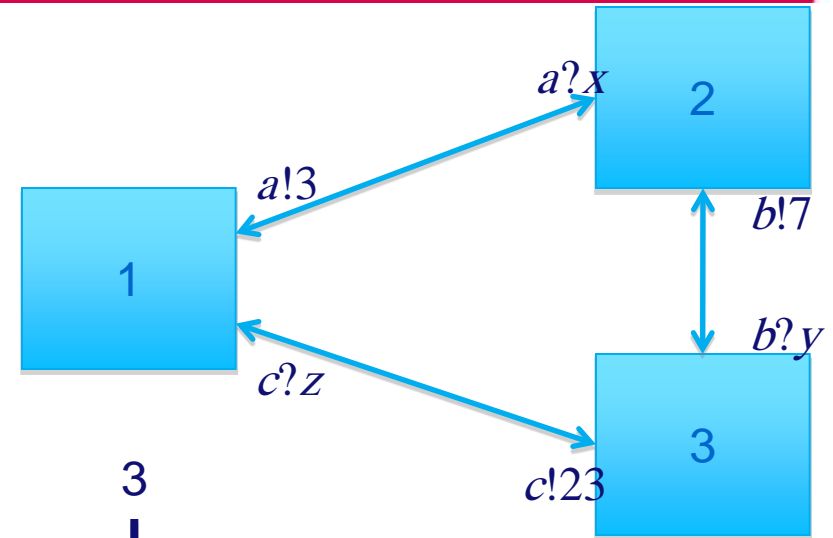
1. Order all processes
2. Propose interaction to higher parties
3. Commit to proposals from lower parties
4. (Dis)agree to commits as soon as possible



Buckley and Silberschatz, 1983
Ramesh, 1987

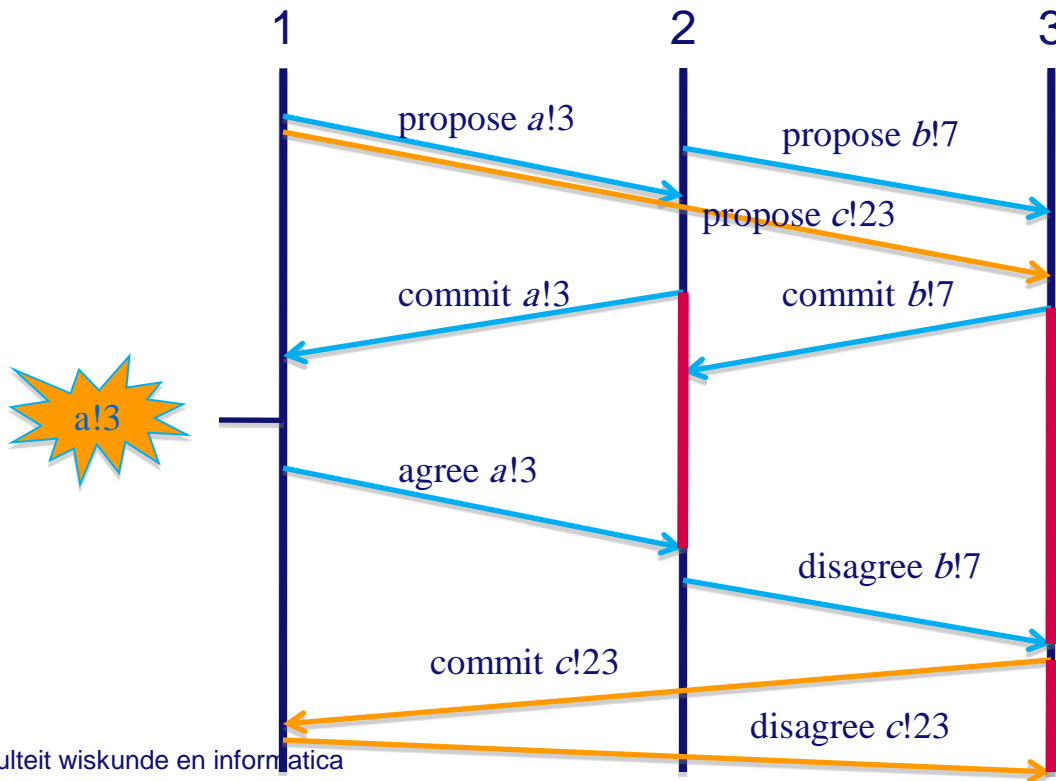
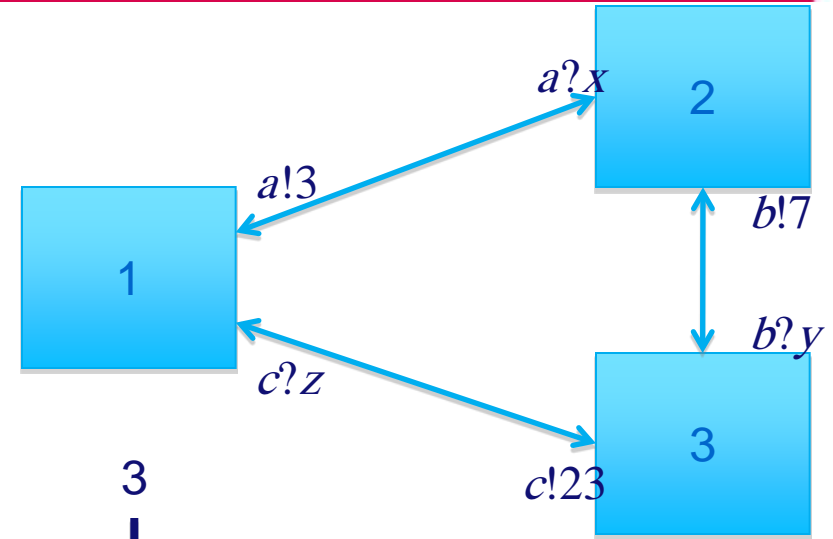
Solution.

1. Order all processes
2. Propose interaction to higher parties
3. Commit to proposals from lower parties
4. (Dis)agree to commits as soon as possible

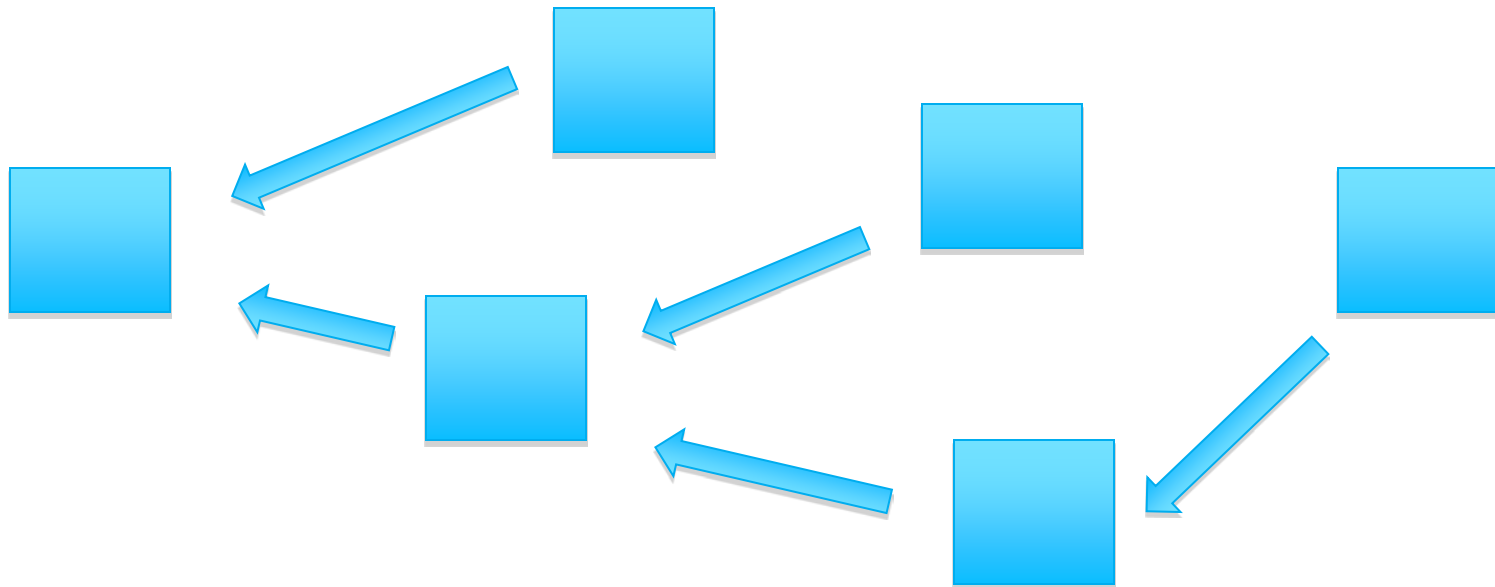


Solution.

1. Order all processes
2. Propose interaction to higher parties
3. Commit to proposals from lower parties
4. (Dis)agree to commits as soon as possible



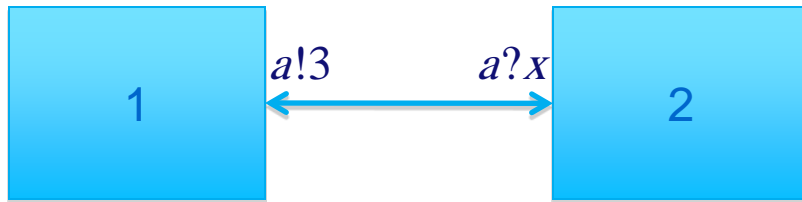
Commit dependencies are non cyclic.



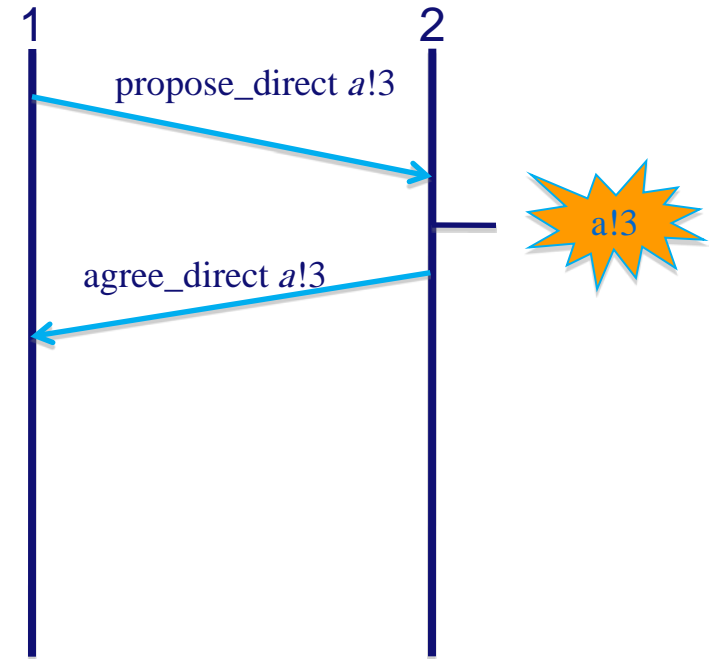
Waiting commits to be (dis)agreed.

Complexity: three messages per proposed interaction.

Optimisations are often possible: 2 messages.



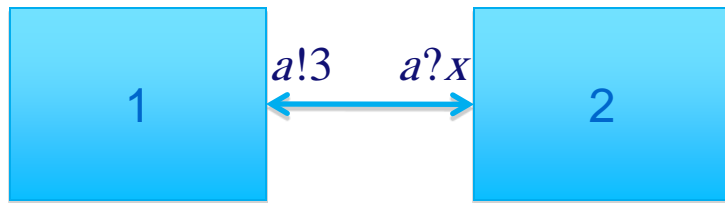
$a!3$ does not occur in a choice.



Theorem: Implementation by 2 messages preserves testing equivalence (LOTOS, 1988)

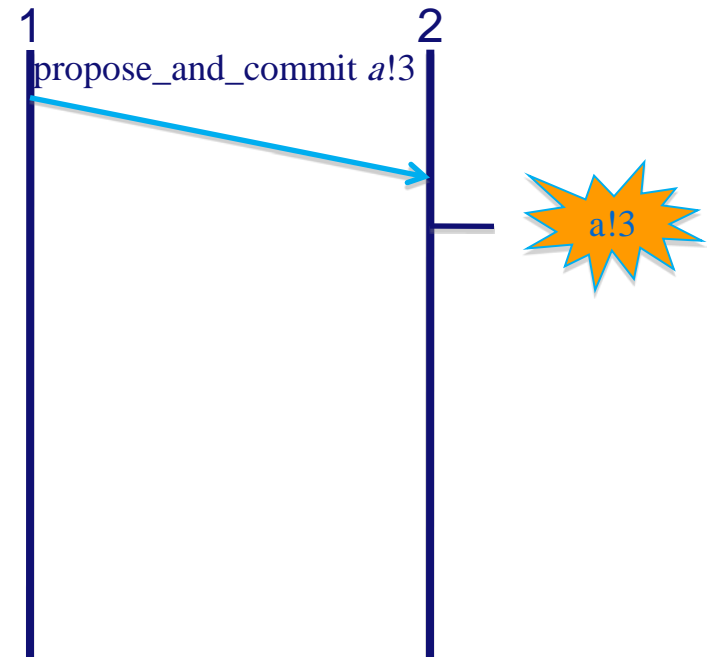
This is the communication scheme in OCCAM (Transputer)

Optimisations are often possible: 1 message.



$a!3$ does not occur in a choice, and has no subsequent activity.

Typical example: $p \parallel a!3.\delta$



Conclusion.

Asynchronous communication

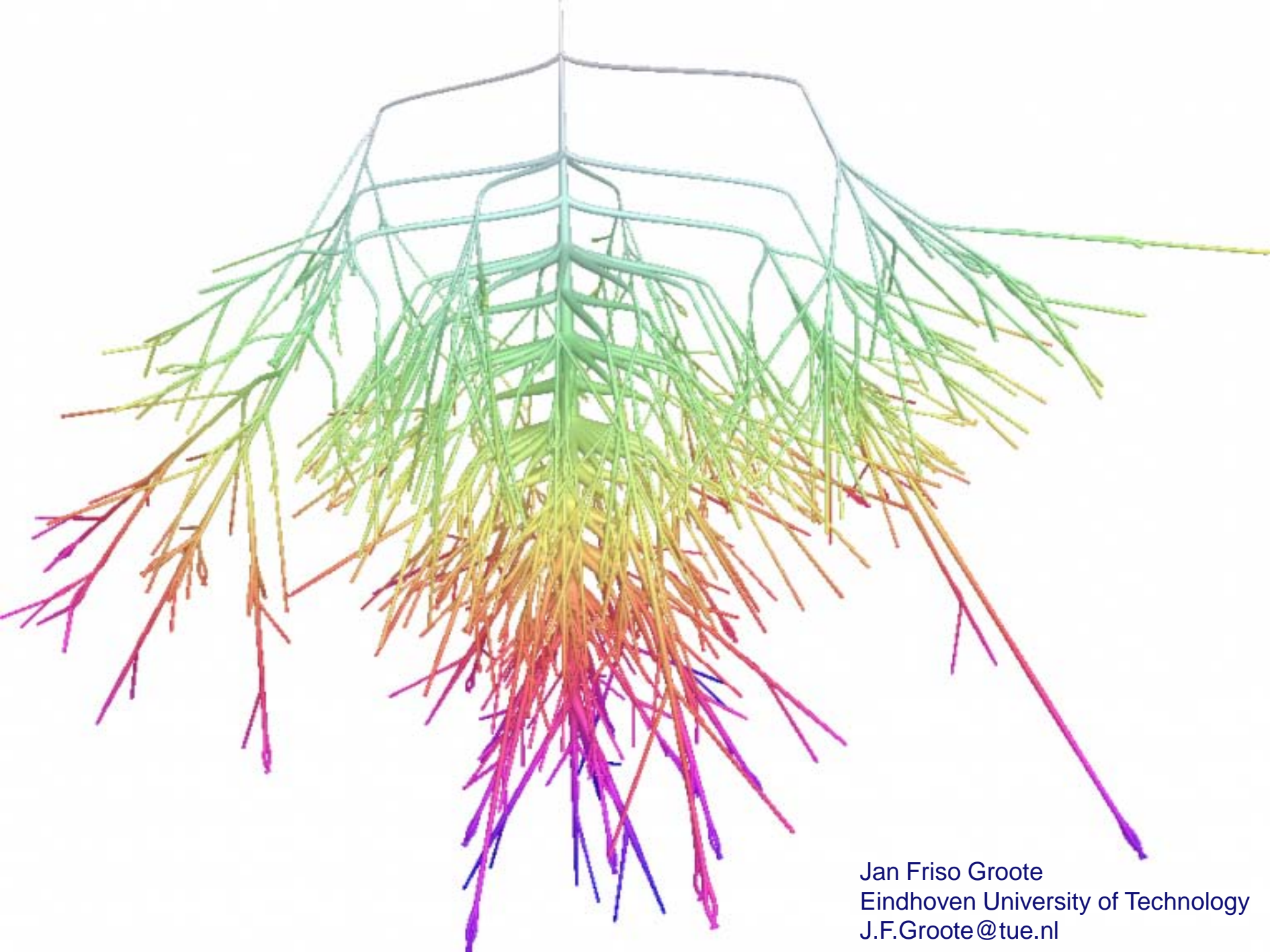
\approx

Synchronous communication

Challenge

Challenge: Implement synchronous models efficiently in an asynchronous, distributed way

obtain_resource1.Use_resource1
+
obtain_resource2.Use_resource2
+
receive_cancel_message.Do_something_else
+
..... (further alternatives)



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